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International Cartographic Association(ICA)

Yildiz Technical University

## A research in cartographic labeling to predict the suitable amount of labeling in multi-resolution maps.

**Geomatics Engineering Department** 

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Cartographic labeling in multiresolution maps using web services.

> 1. A research in Cartographic Labeling to predict the suitable amount of labeling in Multi-Resolution maps.

> > 2. (No name assigned yet)

### Understanding the map components

There have been several works and efforts towards making the <u>best computerized map generalization</u>.

An important part of the generalization process, axiomatically, for a map is to <u>understand its components</u>.

Through <u>labeling</u> the user can understand the map a lot easier and more accurate-

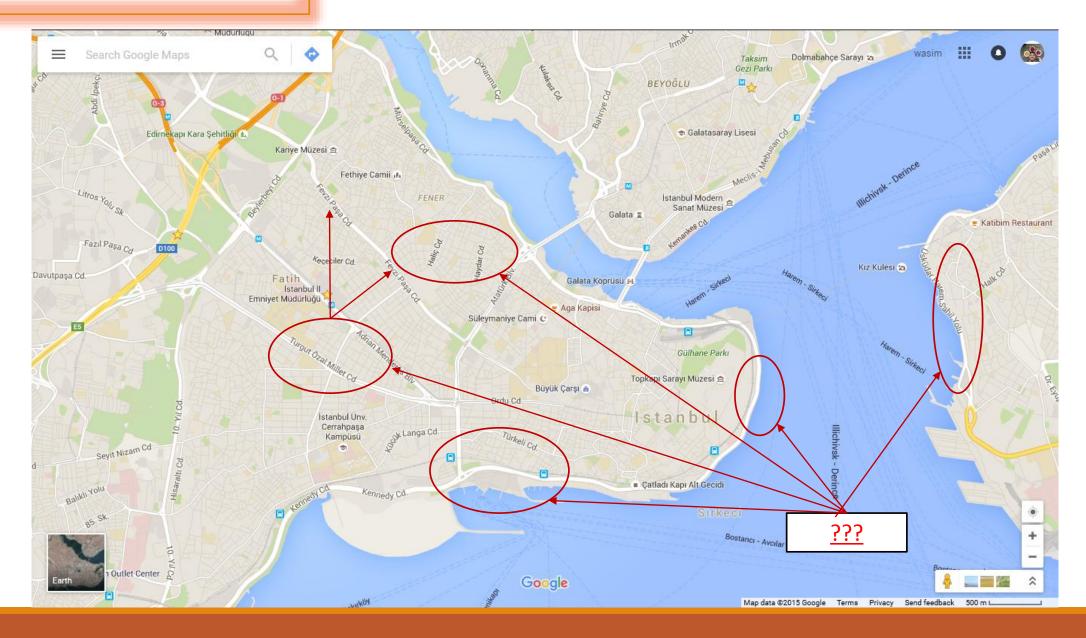
### Map Analysis

We analyzed the best multiresolution map services, such as Google Maps, Yandex Map, OpenStreetMap, Bing Map and others.

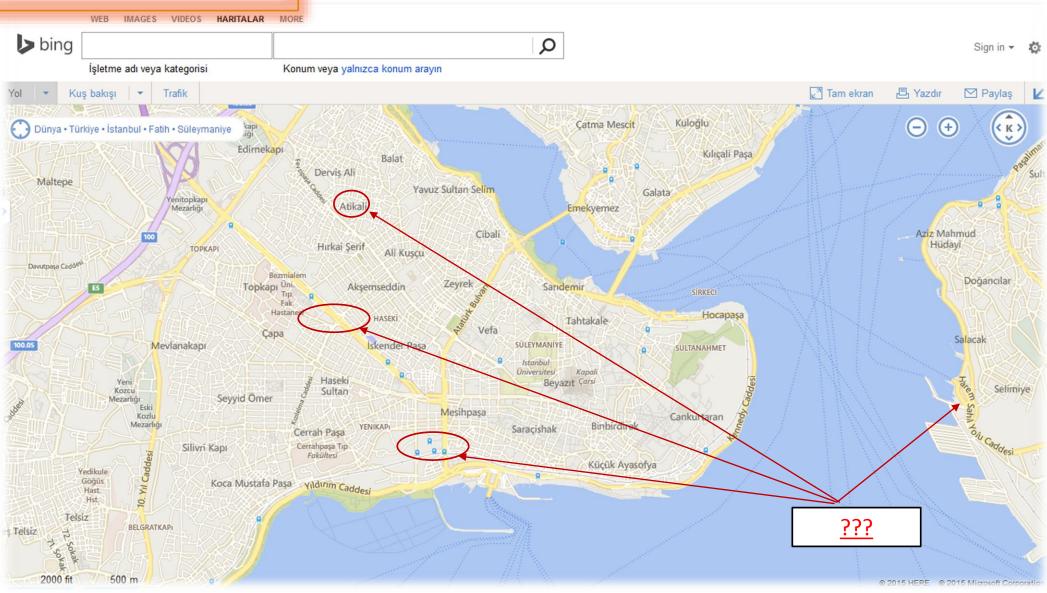
Most if not all of the used popular online map services <u>do not</u> <u>share their used algorithms or models</u>, thus forced us to analysis and simulate their displaying system using techniques such as the <u>artificial neural network</u> means and tools.

# **Online web map browsers**

### Google map sample



### Bing map sample



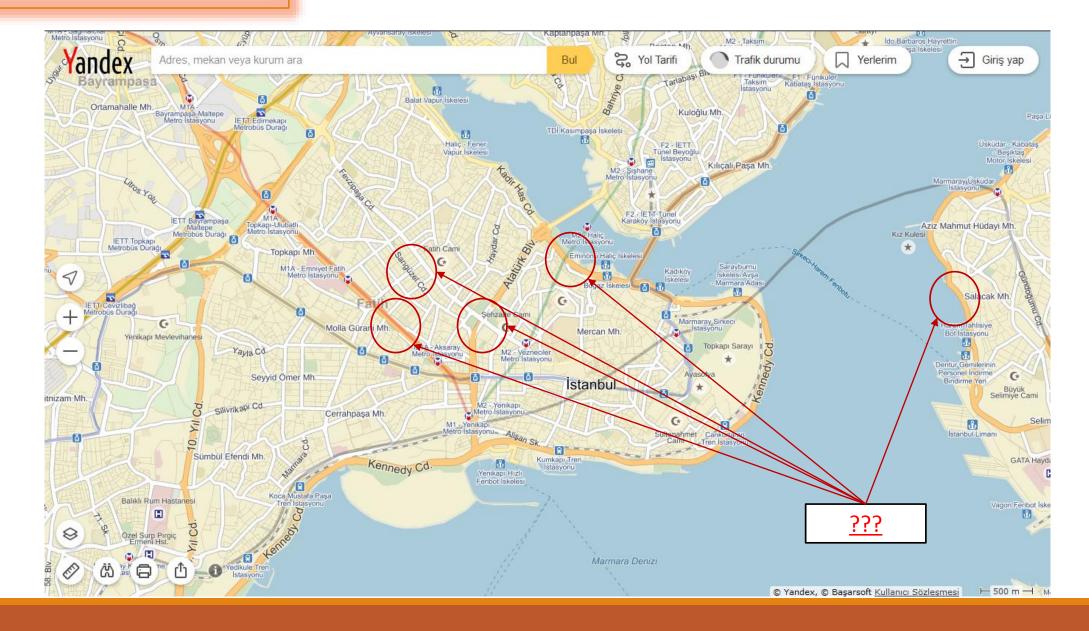
#### OpenStreetMap sample S OpenStreetMap Edit -Export GPS Traces User Diaries Copyright Help About Sign Up History Log In Taksim Search Where am 17 Dayıanıpaşa Kabatas Tepebași Cihangir Mh 5 Beyoğ Şişhan Arap Ca Topkaki Ulubatli Unkapan Karako 11 6 avutpasa Emniyet - Fai caddes Kennedy Caddes Sirkeci Vezneci Aksaray LCaddes du Caddes/ Gedikpaşa sijiwnikapi caddesi Avrasya Tup Tunel vrasya Tüp Tüneli a Tüp Tüneli Istanbul nikar rtara University Yenikap Kuruk Langa Gaddes Kennedy Caddesi Kumkapi Kennedy Caddee Kennedy Cadd ??? Yenikapı Koca Mustafa Pasa miting Alanı 500 m Yedikule

Kazlıçeşmi

2000 ft

OpenStreetMap contributors 
Make a Donation

### Yandex sample



### **General Goals**

# Main goal will be focus on reducing the labeling deficits of the previous mentioned online map browsers and giving the map user the best understood for the street map product.

These works witness a lot of unnecessary data lost

Focus mostly on point labeling

Less concentration on real time mapping but more on static hardcopy map production

Focusing on the legibility problems (amalgamation, displacement, etc.)

### Our study's (Goals)

## Online Multiresolution streets map products.

(for map users, extracting the most required information from the map, their needs should differ in every level of detail) Giving more <u>significant</u> to the <u>displayed feature</u> at every LOD, and considering the <u>amount</u> of displayed features

(the <u>road types</u> which is going to be presented at that certain zoom level should be considered, also trying to make <u>the amount of the displayed</u> <u>data</u> sufficient enough without any shortage or excessive.) A methodology for better labelling with the use of intellectual hierarchy.

composing a formula using some values that we found.

### **Our study (Approach)**

### Study Area

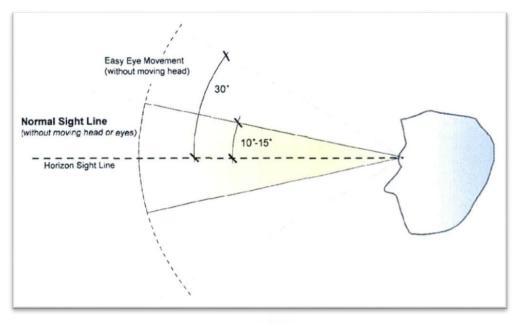
- We choosed a study area for testing contains a well established attribute table and a complete vector data represents the street layer in that area.
  - We controlled the data set and made some data enrichment for it's needed contents.

### Formula

 to predict the most suitable amount of labels for the road features to be displayed also determining the important features that have to be labeled at each LOD.



### **Calculating values**

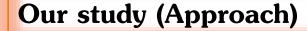


$$\alpha = 2 \arctan \frac{d}{2f}$$

The human vision must be first considered, providing the necessary context to evaluate the area the eye can focus in while the map user uses the digital map.

When the map users look at the map through their devices, they look through a field of view.

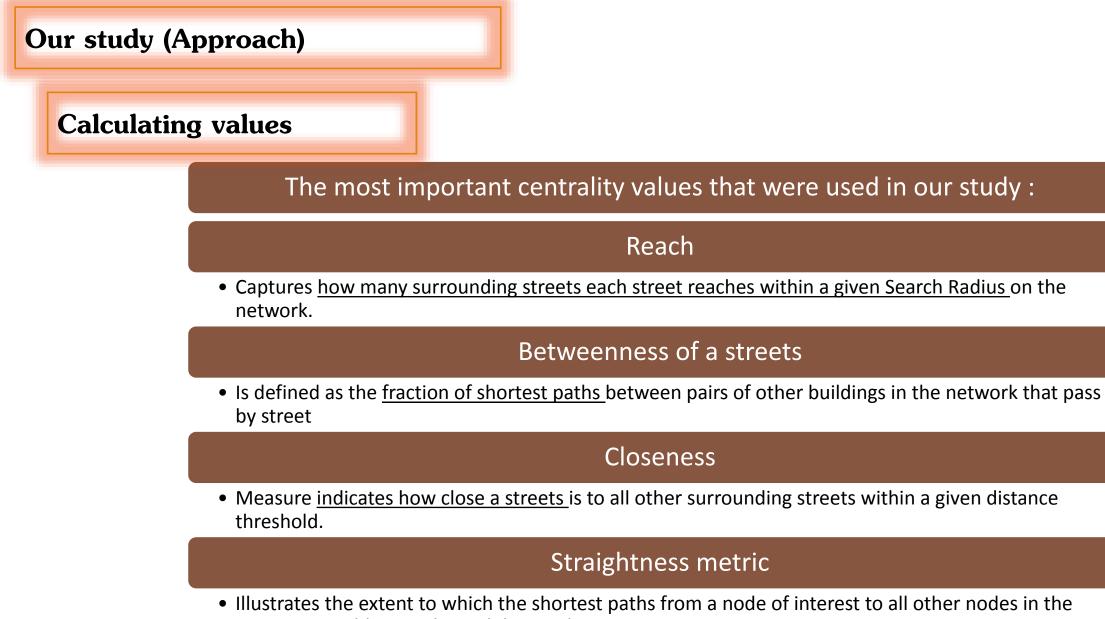
Field of view is the extent of the observable world that is seen at any given movement.



**Calculating values** 

We run a calculation for the features to determine <u>their centrality values</u>.

Also we considered some <u>other values</u> for each street feature, such as their <u>length</u>. We defined the <u>suitable road types</u> <u>and classes</u> to be shown that we believe would give the map user the best understanding for the map at every zoom level.



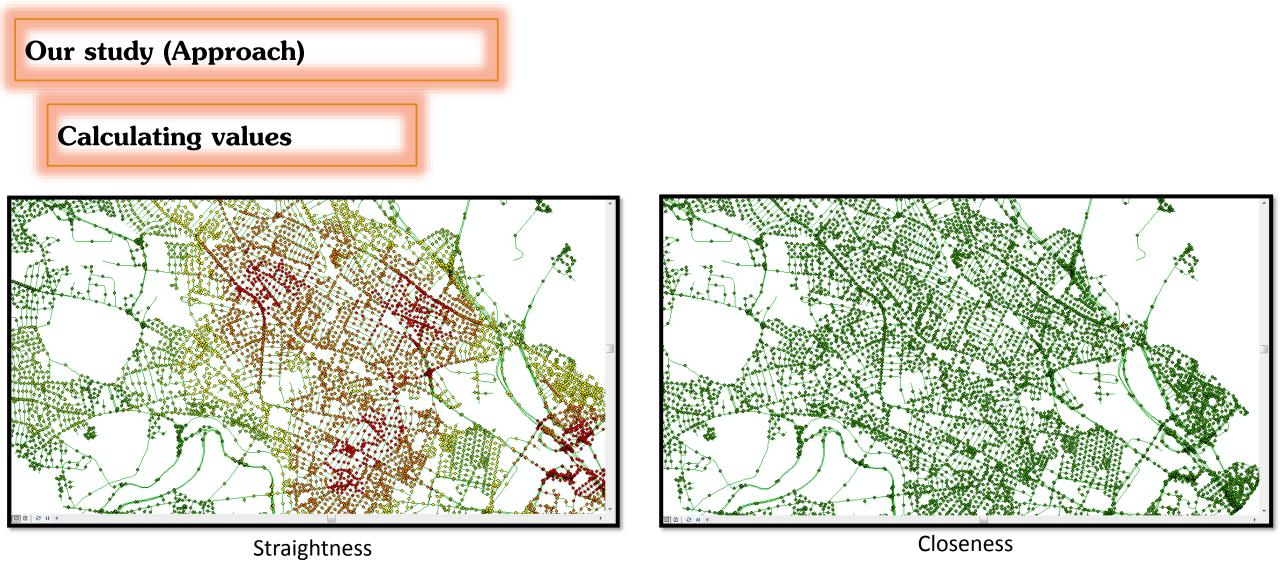
system resemble straight Euclidian paths.



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### **Our study (Approach)**

We will use the values we calculated before and generate it in our <u>formula to produce hierarchy to label the features by</u> <u>its importance</u> as the most important factor next to other factors that will be consider in street labeling.

We will decide the importance of each field by applying some <u>Analytic Hierarchy Processes</u> such as (AHP).

Our formula is expected to display the <u>best amount of</u> <u>labels</u> along with the <u>most important road features</u> to be labeled at every level of detail.

The elements will be used to insure that are	(1) The artificial neural system principles means and tools, the actual number of road objects and actual number of the labels displayed at each level of detail extracted from the used map services
	(2) The field of view (area) of the displaying screen

(3)The values that we have calculated for every feature in the network.

### The expected Results

The composed formula will be expected to provide us <u>the</u> <u>significantly important</u> <u>road labels</u> considering the previous mentioned elements at every LOD.

The formula is expected to be more accurate and suitable for the <u>online</u> <u>multi-resolution map</u> production. The composed formula will be compared with the radical law equation of Topfer and Pillewizer (1966) to predict the <u>suitable number of</u> <u>features needed to be</u> <u>shown at the target</u> <u>scale.</u> Cartographic labeling in multiresolution maps using web services.

> A research in Cartographic Labeling to predict the suitable amount of labeling in Multi-Resolution maps.

2. (No name assigned yet) but it should be about modeling and visualizing cartographic

maps

