



# The Web Mercator Projection: A Cartographic Analysis

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# Introduction

- Web-based mapping services are using a modified version of Mercator Projection that is called Web Mercator.
- The WGS84 ellipsoid is transformed to the map by using spherical projection equations.
- The resulting projection is no more conformal.
- Neither Mercator nor the Web Mercator is not suitable for portraying the whole earth.

# Map Projection

- A transformation from the reference surface to the map (Forward Transformation)

$$x = x(\varphi, \lambda)$$

$$y = y(\varphi, \lambda)$$

- Reference surface: Ellipsoid or sphere

- Inverse transformation (from the map to the reference surface)

$$\varphi = \varphi(x, y)$$

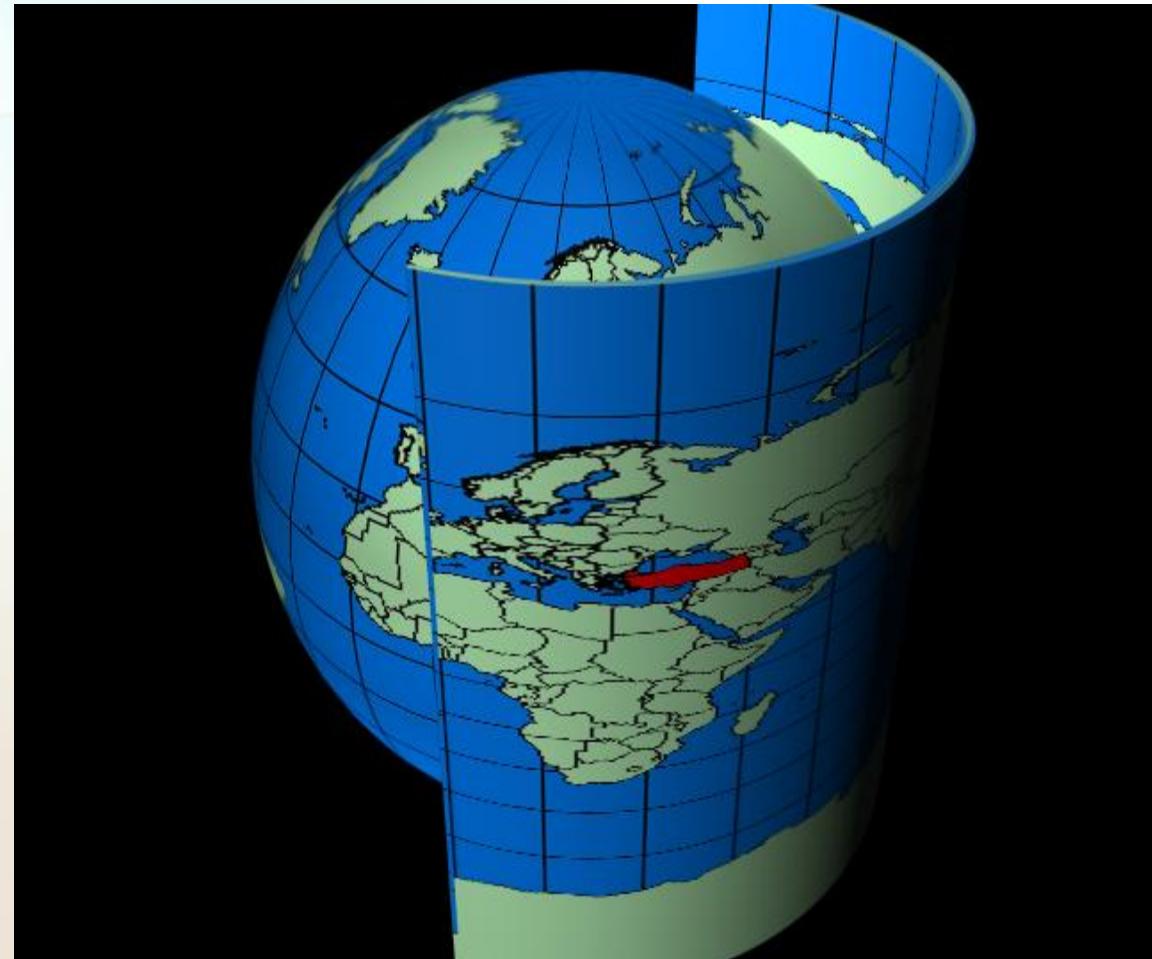
$$\lambda = \lambda(x, y)$$

# Cylindrical Projections

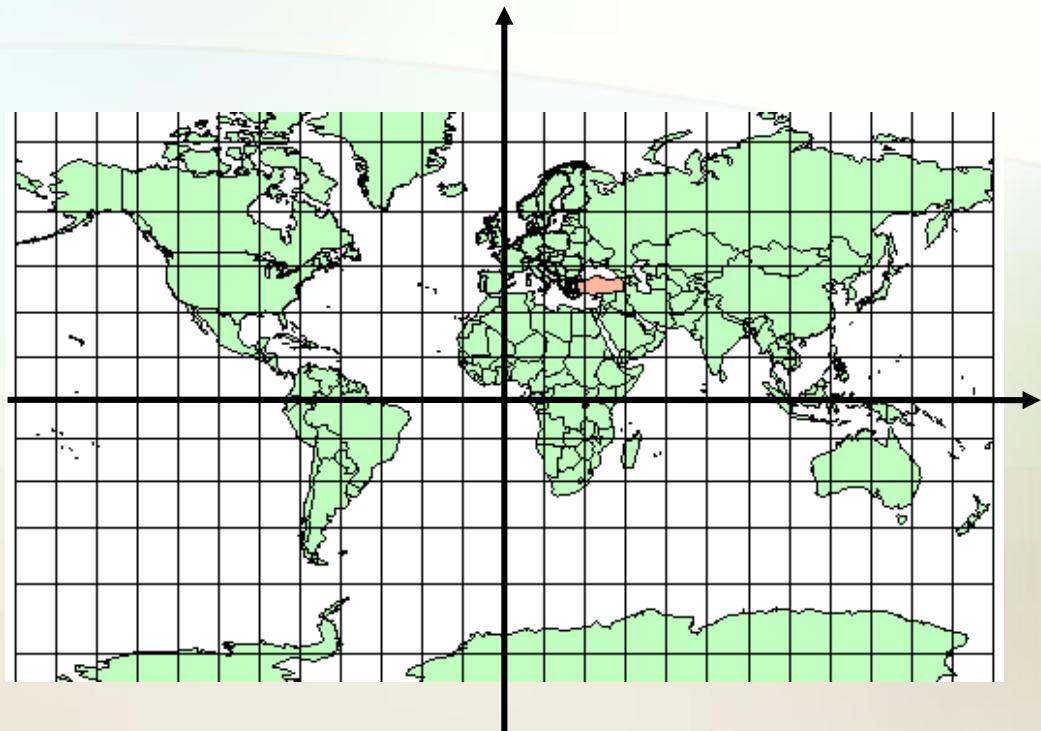
Sphere

→ Cylinder

→ Plane



- The rectangular earth in cylindrical projection enables a suitable coordinate system.
- High distortion occurs towards poles!
- A conformal projection is required to portray the objects of the real world similarly.
- This is important when presenting man-made objects such as buildings in aerial imagery.



$$x = f_1(\lambda)$$

$$y = f_2(\phi)$$

# Mercator

- One of the well-known projections
- Cylindrical and conformal.
- Rhumb lines are depicted as straight lines.
- One or two standard parallels
- areas towards poles are distorted too much.
  - At  $60^{\circ}$  latitude areas are 4 times exaggerated.
- Polar areas can not be shown.
- Widely used.

- Forward transformation:

$$x = R\lambda$$

$$y = R \ln \tan \left( \frac{\pi}{4} + \frac{\varphi}{2} \right)$$

- Linear distortion:

$$m = \frac{1}{\cos \varphi}$$

Spherical  
One standard parallel

- Forward transformation:

$$x = a\lambda$$

$$y = a \ln \tan \left( \frac{\pi}{4} + \frac{\varphi}{2} \right) \left( \frac{1 - e \sin \varphi}{1 + e \sin \varphi} \right)^{\frac{e}{2}}$$

- Linear distortion:

$$m = \frac{a}{N \cos \varphi}$$

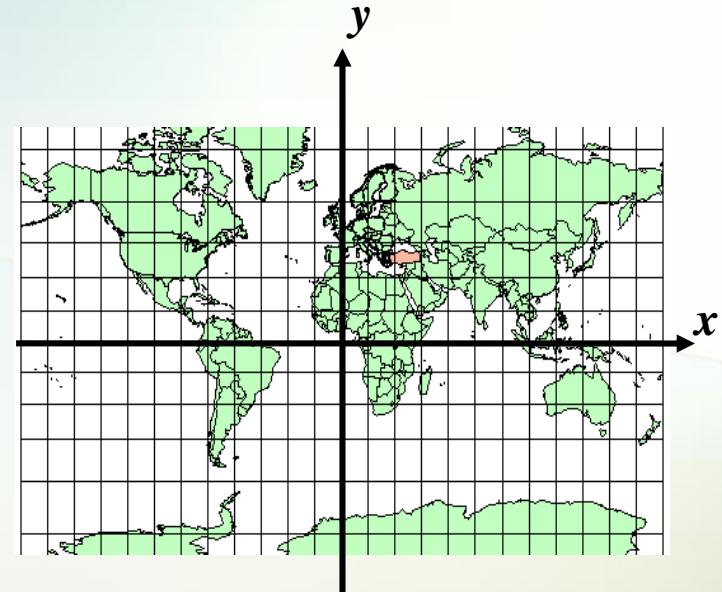
Ellipsoidal  
One standard parallel

# Web Mercator

- WGS84 ellipsoid is transformed to the map plane with spherical equations.
- No more conformal

$$x = a\lambda$$

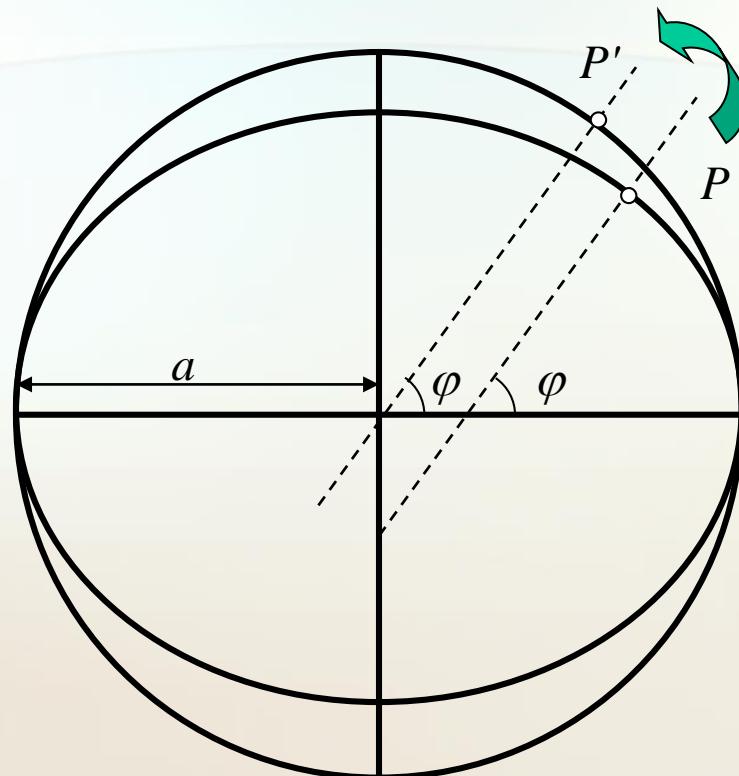
$$y = a \ln \tan \left( \frac{\pi}{4} + \frac{\varphi}{2} \right) \left( \frac{1 - e^2}{1 - e^2 \sin^2 \varphi} \right)^{\frac{1}{2}}$$

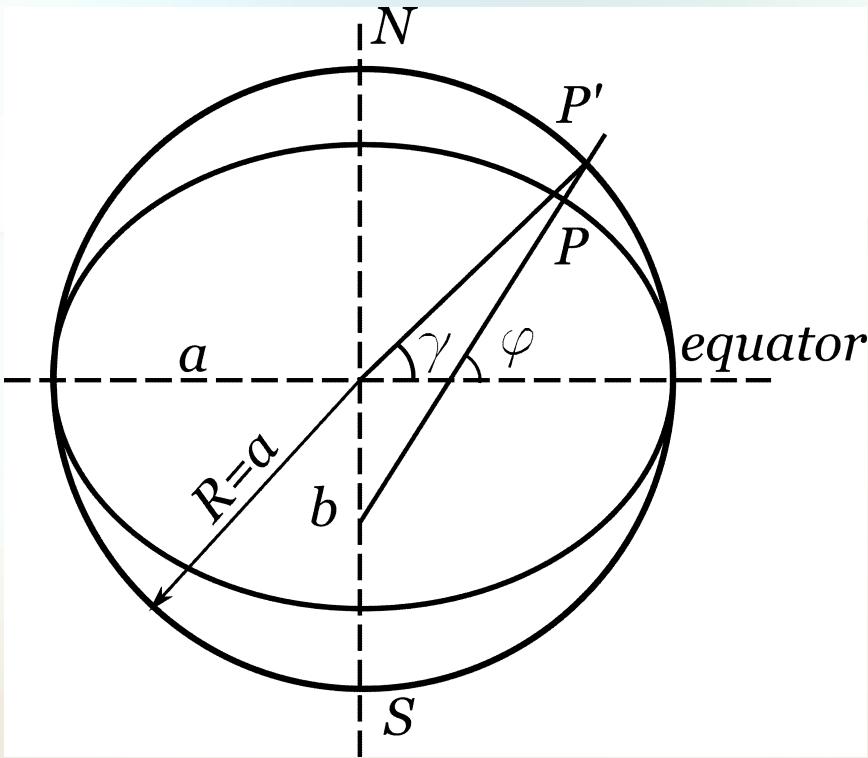


$$x = a\lambda$$

$$y = a \ln \tan \left( \frac{\pi}{4} + \frac{\varphi}{2} \right)$$

# Latitude?

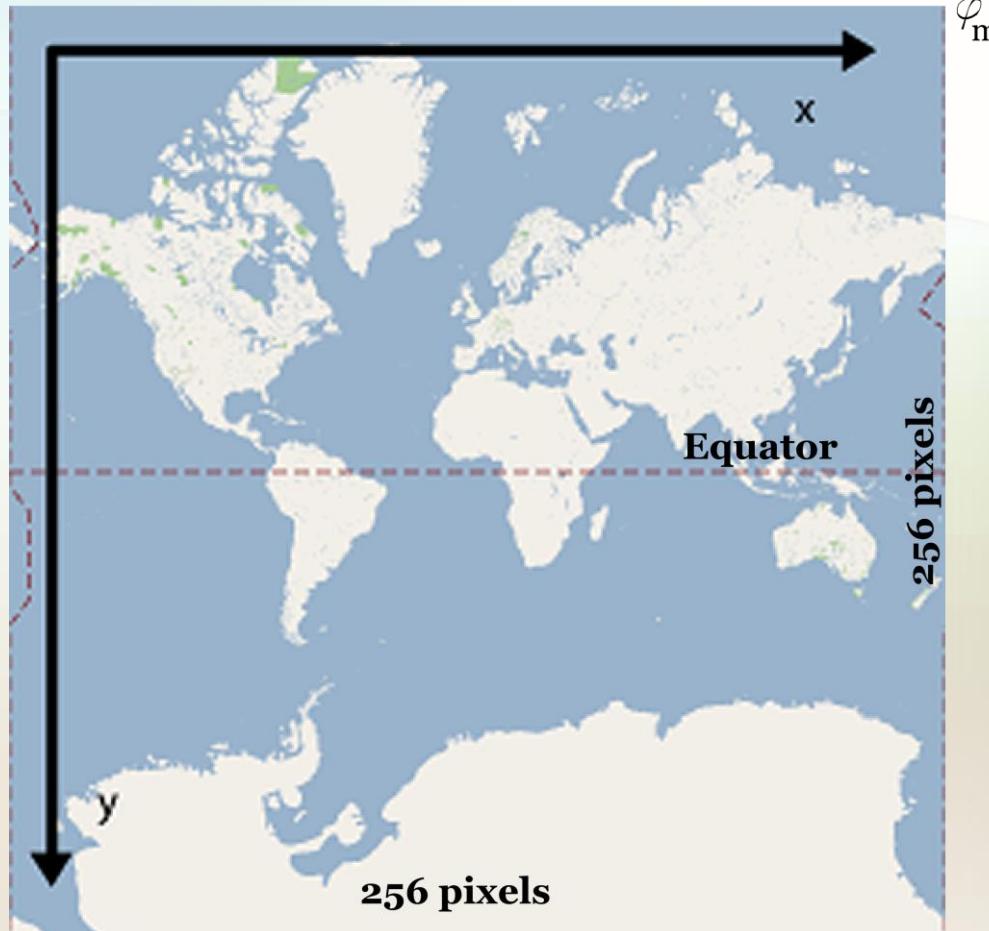




$$x = \frac{128}{\pi} 2^n (\lambda + \pi)$$

$$y = \frac{128}{\pi} 2^n \left( \pi - \ln \tan \left( \frac{\pi}{4} + \frac{\varphi}{2} \right) \right)$$

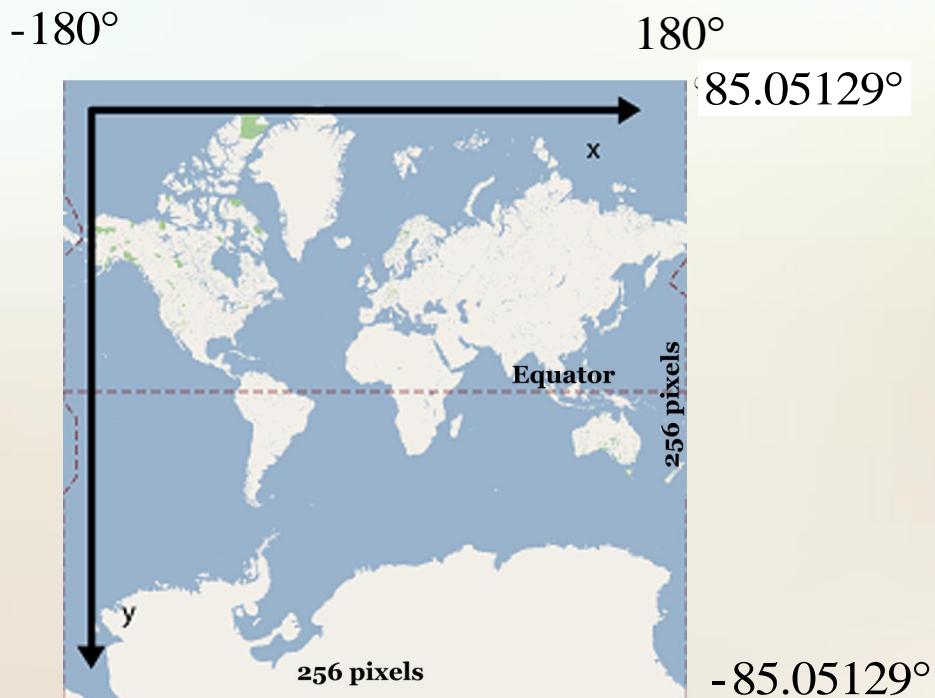
Coordinate system is shifted and scaled!



setting  $y = 0, n = 0$

$$\ln \tan\left(\frac{\pi}{4} + \frac{\varphi_{\max}}{2}\right) = \pi$$

$$\varphi_{\max} = 2 \arctan e^\pi - \frac{\pi}{2} = \pm 85.05129^\circ$$



- The web mapping services use zoom levels up to 18.
- The spatial resolution of 1 pixel ranges from 156 km at zoom level 0 to 0.60 m at zoom level 18.

$$1 \text{ pixel} = \frac{\pi a}{2^{n+7}} \text{ meters}$$

# Inverse Transformation

$$\varphi = 2 \arctan e^{\frac{\pi - \frac{\pi y}{2^{n+7}}}{2}} - \frac{\pi}{2}$$

$$\lambda = \frac{\pi x}{2^{n+7}} - \pi$$

# Projection Distortions

- For this purpose metric projection equations should be used.

$$x = a\lambda$$

$$y = a \ln \tan \left( \frac{\pi}{4} + \frac{\varphi}{2} \right)$$

- Distortions along meridians and parallels:

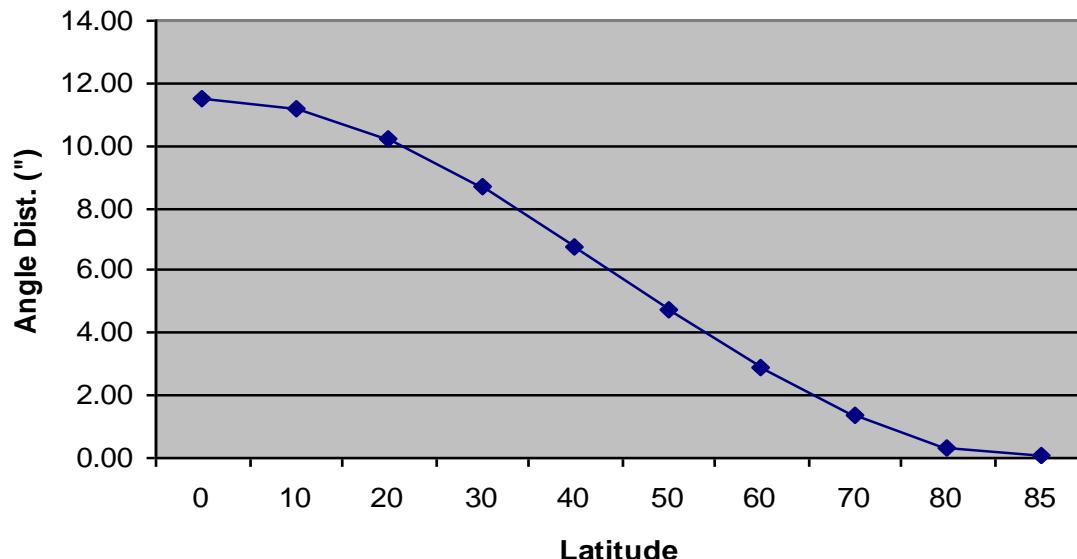
$$h = \frac{1}{M} \frac{dy}{d\varphi} = \frac{a}{M \cos \varphi}$$

$$k = \frac{1}{N \cos \varphi} \frac{dx}{d\lambda} = \frac{a}{N \cos \varphi}$$

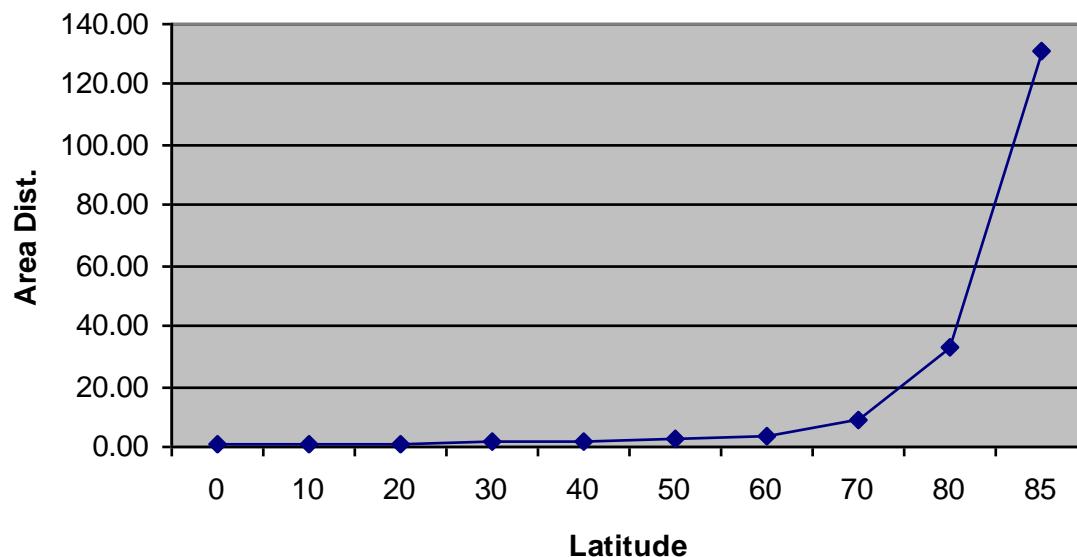
# Distortions

$\varphi$	$h$	$k$	$p$	$\omega$
0°	1.006739	1.000000	1.006739	11' 32.7"
10°	1.021961	1.015324	1.037621	11' 11.9"
20°	1.070092	1.063761	1.138322	10' 11.9"
30°	1.159566	1.153734	1.337830	8' 40.0"
40°	1.308756	1.303601	1.706096	6' 47.1"
50°	1.556989	1.552665	2.417482	4' 46.8"
60°	1.998334	1.994973	3.986623	2' 53.6"
70°	2.917448	2.915150	8.504798	1' 21.3"
80°	5.741212	5.740046	32.95482	0' 21.0"
85°	11.43612	11.43554	130.7782	0' 5.3"

Angle Distortion

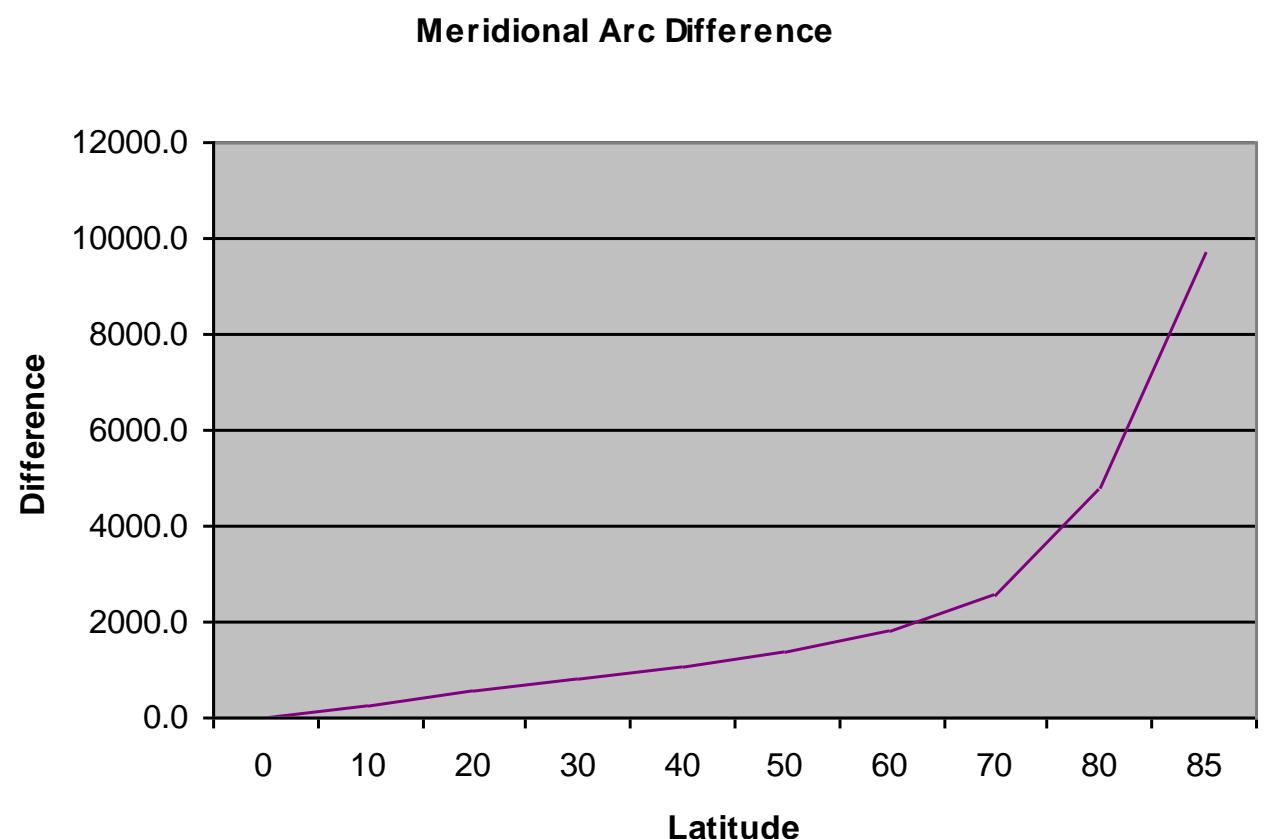


Area Distortion



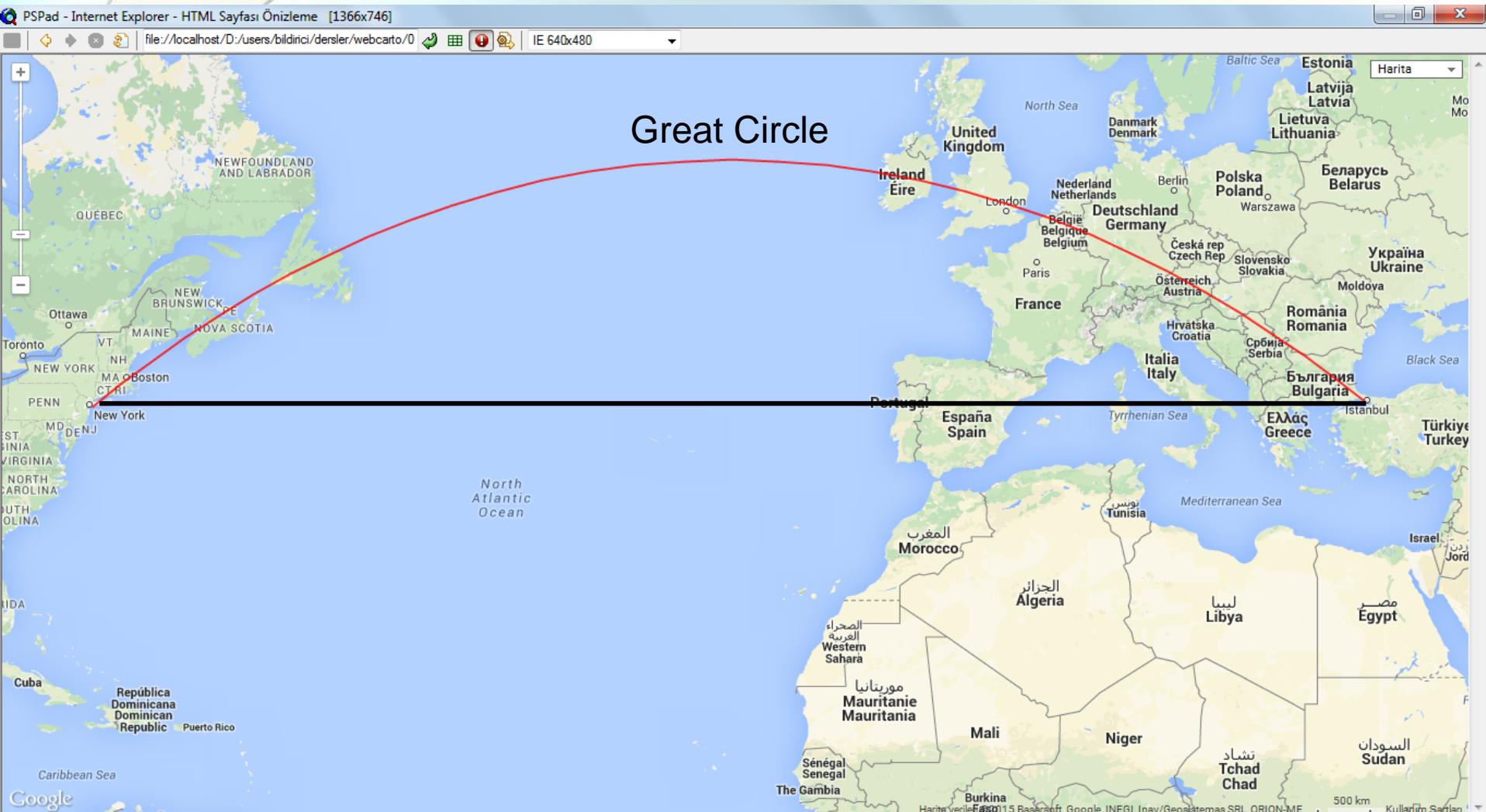
# 1 ° Meridian Arc Comparison

Latitude	WGS84 (m)	Web M. (m)	Mercator (m)	Difference (WM-M) (m)
0°	110574.389	111325.1	111312.0	13.1
10°	110611.187	113216.8	112942.0	274.8
20°	110710.615	118847.7	118310.8	536.8
30°	110860.926	129199.3	128396.9	802.4
40°	111044.261	146399.4	145318.3	1081.1
50°	111238.681	175017.9	173620.6	1397.2
60°	111420.728	226085.3	224268.1	1817.2
70°	111568.259	333556.5	330999.0	2557.5
80°	111663.201	675090.0	670299.7	4790.3
85°	111687.001	1424698.4	1414946.5	9751.9



# An Alternative: Virtual Globe

- Polar areas can be mapped
- Less, or no distortions (depending on the view point)
- Great circles are represented correctly.



Great Circle

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Image Landsat

Data SIO, NOAA, U.S. Navy, NGA, GEBCO  
US Dept of State Geographer

Görüntü Tarihi: 4/10/2013 Enlem 39.898498° Boylam -21.230041° yükseklik -4358 m göz hızı 6852.44 km

N

Google earth

# Conclusions

- Despite being unsuitable in terms of map projection distortions, Web Mercator Projection is beneficial in terms of computer graphics and tiling system.
- The graticule appears rectangular that matches the Cartesian coordinates on the map plane.
- Virtual globe representations are another way of web-based visualization.
- Google supported earth view in the previous version of Google Maps API, and later launched Google Earth API. Both are deprecated now.
- Since globe representation is a 3D visualization not affected by map projection distortions, their use is beneficial together with 2D map.
- Such possibilities can help map users to understand changes in geometry caused by map projection.

# Thank you for your attention!

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