

Derivation of Topographic maps from Laser Scanning Data

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Introduction

Applications' demands are made about:

More maps Quality (better maps) Currency (up-to-date maps) Accuracy (precise maps) Cost (Cheaper maps) Variety (different maps)

New map production's technologies

The role of cartographic knowledge as applied to map production:

Map design Symbolization Text and label placement Generalization Color selection

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Introduction

Maps can be grouped in three categories:

- Cadastral maps, city maps and technical planes
- Topographic maps: showing the ground surface with its features and objects, such as rivers, buildings, vegetation and roads..... etc.
 Topographic maps have scale between about 1:25000 and 1:100000.
- Geographic maps and thematic maps.

(Kraus, 1995)



Introduction

Topographic data acquisition technologies:



Airborne Laser Scanning (ALS)

- Laser scanning systems are active
 - They can work day and night
 - No problems in areas without texture (dark shadows)
- High vertical accuracy
- Density
- Automation
- Fast delivery time



http://www.optech.ca/



ALS-Data Re-sampling

 Processing of irregularly distributed points as obtained from laser scanning takes more time than processing of regularly distributed ones.

 Most procedures start by re-sampling the laser data into a regular raster.

(2D array of elevation values)







Topographic Modeling

- DSM: Digital surface model
- DTM: Digital Terrain model
- nDSM: normalized digital surface model





Contour lines

• The primary format for representing elevation data





Depending on:

- DTM's grid size (Re-sampling)
- DTM's resolution (points density)







4 points/m²





• Scale of the map



• Cartographic generalization will be needed to obtain smooth contour lines and optimal representation of the landscape

1: 2,500 photogrammetric contour map (Tokyo city planning map, 1999)

2 m interval contour map based on a 2 m grid DTM



Overlap of cross sections based on a photogrammetric contour map and laser DTM





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Topographic land-cover map

 Using ALS-data and additional data (Orthophoto) many attributes can be obtained to derive land-cover classes.

1. Terrain slope (Gradient):



2. Level deviation (Sigma):

 σ_7



Topographic land-cover map

3. Echo-ratio:

 $echo - ratio = \frac{n3D}{n2D} \times 100$

vegetation index)





4. Vegetation index (from orthophoto): VARI (Visible Atmospherically Resistand Index)
Or NDVI (normalized difference



5. nDSM

Topographic land-cover map - Classification

Derived attributes:		
Terrain slope		
Level deviation		
Echo-ratio		
nDSM		
VARI/NDVI		

Classification methods Maximum –likelhood- method Supervised classification Unsupervised classification

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	Class	Attribute	Conditions
		Echo-ratio	<73.8%
e.g.	Forest	Sigma	<0.48m
		nDSM	>2.25m
		VARI	-0.009 <vari<0.408< td=""></vari<0.408<>









Topographic land-cover map - Generalization

- Land cover map which is derived from ALS-Data and Orthophoto needs to be generalized by cartographers depending on the scale of the map
- In the case of classified land cover classes from ALSdata automated operation are used in generalization:
 - Digital image processing (neighborhood distance, edge detection, ...)
 - Re-sampling
 - Vectorization (Raster to vector)
 - Reclassification (new classes)
 - Simplification (smoothing a line or area boundary)
 - Selection/Elimination



Topographic land-cover map - Generalization

Workflow:



First workflow:





Summary and further work

- Since the airborne laser scanner can measure the elevation under vegetation the topographic information is more detailed than the information obtained from maps drawn by another survey mapping specially in the fine topography of mountains regions.
- Quantitative estimation of topographical change by repeated measurement using an airborne laser scanner is possible.
- Integration between different topographic data acquisition technologies and develop new approaches to derive more precise topographic maps.



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